# SVD RS II (Optional)

STAT3009 Recommender Systems

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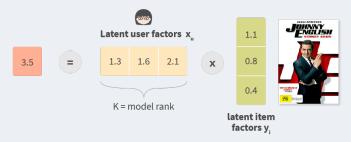
## » Matrix Factorization (MF) Models

- SVD-based collaborative filtering
- \* Alternating Least Squares (ALS) optimization
- \* Coordinate descent methods
- \* Low-rank matrix completion

### » Recall: Matrix factorization

#### The main idea of *matrix factorization*

- \* params → users/items preference
- \*  $inner-production \rightarrow user-item interaction$
- \* (first proposed by **Simon Funk** during the Netflix Prize)



The idea of MF RS (Source<sup>1</sup>). The latent factors  $\mathbf{x}_u$  and  $\mathbf{y}_i$  in the image are denoted as  $\mathbf{p}_u$  and  $\mathbf{q}_i$  in the slides.

Image Source:

- » Recall: Matrix Factorization
- Step 1 Introduce a method with some *parameters* (latent factors)
  - \* Model the user-item interaction as the inner product

$$\hat{r}_{ui} = oldsymbol{p}_u^{\mathsf{T}} oldsymbol{q}_i 
ightarrow r_{ui}$$

Step 2 Estimate the *parameters* by minimizing the regularized *MSE* 

$$\min_{P,Q} \frac{1}{|\Omega|} \sum_{(u,i) \in \Omega} (r_{ui} - \boldsymbol{p}_{u}^{\mathsf{T}} \boldsymbol{q}_{i})^{2} + \lambda \left( \sum_{u=1}^{n} \|\boldsymbol{p}_{u}\|_{2}^{2} + \sum_{i=1}^{m} \|\boldsymbol{q}_{i}\|_{2}^{2} \right) \quad (1)$$

- \* Use *cross-validation* to determine the optimal *hyperparameters*  $(K, \lambda)$ , denoted as  $K^*$  and  $\lambda^*$
- \* Refit the model based on the *full training data* with  $K^*$  and  $\lambda^*$ .
- Step 3 Use the *estimated model* with the *best hyperparameters* to make predictions

### » Design Your Own Recommender System

We also summarize the *steps* to customize a novel Recommender System.

Step 1. Introduce a model (with parameters and hyperparameters) to formulate the rating. For example,

$$\widehat{r}_{ui} = \mu + a_u + b_i + \mathbf{p}_u^{\mathsf{T}} \mathbf{q}_i$$

Step 2. Find an *algorithm* to fit the model with the observed rating set  $\Omega$  and use cross-validation to find the best model:

$$\min_{\theta} \frac{1}{|\Omega|} \sum_{(u,i) \in \Omega} (r_{ui} - \widehat{r}_{ui})^2 + \lambda \operatorname{Reg}(\theta)$$

Step 3. Make a prediction based on the best-tuned model

#### » More on Matrix Factorization

#### MF Proposed by **Simon Funk** (2006)

Other names SVD, Matrix Factorization, Latent Factor Models

$$\hat{r}_{ui} = \boldsymbol{p}_{u}^{\mathsf{T}} \boldsymbol{q}_{i} \rightarrow r_{ui},$$

where 
$$\mathbf{p}_u = (p_{u1}, \dots, p_{uK})$$
, and  $\mathbf{q}_i = (q_{i1}, \dots, q_{iK})$ .

- Issue 1 No explicit regularization over users/items
- Issue 2 Difficult to estimate a good latent factor for users/items with few ratings
- \* Can we propose a new model to address these issues?
- Remark The baseline terms of all models we are going to discuss below are omitted, as they can simply be *added* or considered by *sequential fitting*.

### » More MF: EDA

#### MovieLens:

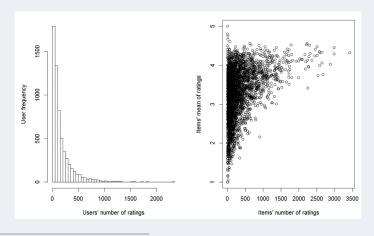


Image source: Bi, X., Qu, A., Wang, J., & Shen, X. (2017). A group-specific recommender system. Journal of the American Statistical Association, 112(519), 1344-1353.

### » More MF: EDA

#### LastFM:

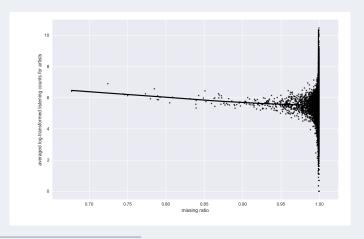


Image source: Dai, B., Wang, J., Shen, X., & Qu, A. (2019). Smooth neighborhood recommender systems. Journal of machine learning research, 20.

### » More on Matrix Factorization: Exploratory Data Analysis

What conclusions can be drawn from the exploratory data analysis?

\* The rating  $(r_{ui})$  is positively correlated with *popularity*.

Popularity

- $* |I_u|$  represents the number of ratings by user-u
- $* \ |\mathcal{U}_i|$  represents the number of ratings by item-i

Can we incorporate the popularity metrics  $|I_u|$  or  $|\mathcal{U}_i|$ , or more generally the rating patterns  $I_u$  or  $\mathcal{U}_i$ , into the Matrix Factorization model?

### » Linear User SVD (L-SVD)

- N-SVD Proposed by Arkadiusz Paterek (2007)
- Motivation The motivation behind N-SVD is to formulate  $\mathbf{p}_u$  based on  $I_u$  (*why?*)
  - \* Assumes a regression model:

$$p_{uk} \sim |\mathcal{I}_u|^{1/2} |\mathcal{I}_u|^{-1} (w_{1k} \mathbb{I}(1 \in \mathcal{I}_u) + \dots + w_{mk} \mathbb{I}(m \in \mathcal{I}_u))$$

- \* (Each rated item influences the user's latent factors)
- \* Then  $\mathbf{p}_u$  can be replaced as:

$$p_{uk} = \tau_u \sum_{i \in I_u} w_{ik}, \quad \mathbf{p}_u = \tau_u \sum_{i \in I_u} \mathbf{w}_i,$$

where  $\tau_u = |\mathcal{I}_u|^{-1/2}$  for notational simplicity.

\* The N-SVD model is:

$$\widehat{r}_{ui} = \mathbf{q}_i^{\mathsf{T}} \left( \tau_u \sum_{i' \in \mathcal{I}_u} \mathbf{w}_{i'} \right).$$

# » Linear User SVD (L-SVD)

- Params  $* \mathbf{Q} = (\mathbf{q}_1, \cdots, \mathbf{q}_m)^\mathsf{T}$  with  $\mathbf{q}_i = (q_{i1}, \cdots, q_{iK})^\mathsf{T}$ \*  $\mathbf{W} = (\mathbf{w}_1, \dots, \mathbf{w}_m)^{\mathsf{T}}$  with  $\mathbf{w}_i = (w_{i1}, \dots, w_{iK})^{\mathsf{T}}$ 
  - Empirical loss function with regularization term:

$$\min_{\mathbf{Q},\mathbf{W}} \frac{1}{|\Omega|} \sum_{(u,i) \in \Omega} \left( r_{ui} - \mathbf{q}_i^\mathsf{T} \left( \tau_u \sum_{i' \in \mathcal{I}_u} \mathbf{w}_{i'} \right) \right)^2 + \lambda \sum_{i=1}^m \left( \|\mathbf{q}_i\|_2^2 + \|\mathbf{w}_i\|_2^2 \right)$$

- $* \lambda$ : weight of regularization term
  - \* K: number of latent factors

#### » L-SVD: Discussion

### Advantages

- S1 Explicitly considers the smoothness across users
- S2 Incorporates popularity into a MF model
- S3 Leverages ratings from other users to estimate latent factors for users with sparse ratings

### Disadvantages

- W Less flexible in modeling users' latent factors.
- \* For example, when two users have rated the same set of items, say (1,2,3), their latent factors will be identical!

#### Potential Solution

Sol We can combine the strengths of SVD and L-SVD: by retaining both user-specific latent factors and item-aggregated latent factors → SVD++

Note that there is a trade-off between model flexibility and estimation complexity.

SVD++ Proposed by Yehuda Koren (2008)

Model SVD++ integrates SVD and L-SVD:

$$\widehat{r}_{ui} = \mathbf{q}_i^{\mathsf{T}} ig( \mathbf{p}_u + au_u \sum_{j \in \mathcal{I}_u} \mathbf{w}_j ig).$$

Empirical loss function with regularization term:

$$\begin{aligned} \min_{\mathbf{P}, \mathbf{Q}, \mathbf{W}} \frac{1}{|\Omega|} \sum_{(u, i) \in \Omega} \left( r_{ui} - \mathbf{q}_i^{\mathsf{T}} \left( \mathbf{p}_u + \tau_u \sum_{j \in \mathcal{I}_u} \mathbf{w}_j \right) \right)^2 \\ + \lambda \left( \sum_{i=1}^m \left( \|\mathbf{q}_i\|_2^2 + \|\mathbf{w}_i\|_2^2 \right) + \sum_{u=1}^n \|\mathbf{p}_u\|_2^2 \right) \end{aligned}$$

**Params** 

- \* User latent factors: P
- \* Regression latent factors: W
- $^{ ext{HP}}$  \*  $\lambda$ : regularization strength
  - \* K: number of latent factors

## » Nonnegative Matrix Factorization (NMF) (Optional)

- NMF Introduced by **Paatero** and **Tapper** (1994), and further developed by **Lee** and **Seung** (1999)
- Model The predicted rating is given as:

$$\hat{r}_{ui} = oldsymbol{p}_u^{\mathsf{T}} oldsymbol{q}_i pprox r_{ui}$$

Formulation Empirical loss function with nonnegative constraints:

$$\min_{\mathbf{P},\mathbf{Q}} \frac{1}{|\Omega|} \sum_{(u,i) \in \Omega} (r_{ui} - \boldsymbol{p}_u^{\mathsf{T}} \boldsymbol{q}_i)^2 + \lambda \operatorname{\mathsf{Reg}}(\mathbf{P},\mathbf{Q}), \quad \mathbf{P} \geq \mathbf{0}; \mathbf{Q} \geq \mathbf{0}$$

# » Group SVD (gSVD)

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Group MF Introduced by Bi, et al. (2017)
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Grouping Pre-computed group assignments for users and items

User Group Each user u is assigned to a group with ID  $v_u$  Item Group Each item i is assigned to a group with ID  $j_i$ 

Model The predicted rating is given as:

$$\hat{r}_{ui} = \left(oldsymbol{p}_{u} + oldsymbol{s}_{
u_{u}}
ight)^{\intercal} \left(oldsymbol{q}_{i} + oldsymbol{t}_{j_{i}}
ight) pprox r_{ui}$$

# » Smooth SVD (sSVD)

- SSVD Introduced by **Dai, et al.** (2019)
- Weight Pre-computed similarity weights between pairs of users and items
  - User Sim  $w_{u,u'}$  represents the similarity between users u and u' Item Sim  $w_{i,i'}$  represents the similarity between items i and i'
  - Model The predicted rating is given as:  $\hat{r}_{ui} = \mathbf{p}_u^{\mathsf{T}} \mathbf{q}_i \approx r_{ui}$ 
    - Using *neighborhood* ratings to estimate (u,i), with weighted regularization:

$$\min_{\mathbf{P},\mathbf{Q}} \frac{1}{nm} \sum_{u=1}^{n} \sum_{i=1}^{m} \sum_{(u',i') \in \Omega} w_{u,u'} w_{i,i'} (r_{u'i'} - \mathbf{p}_{u}^{\mathsf{T}} \mathbf{q}_{i})^{2} + \lambda \mathsf{Reg}(\mathbf{P},\mathbf{Q})$$

### » MF / SVD models

#### Advantages of SVD-/MF-based Methods

- Widely adopted in both industry and academic research
- + Exhibits competitive performance
- Amenable to efficient implementation using parallel computing architectures
- Achieves state-of-the-art (SOTA) performance when only rating data is available
- Most models suffer from cold-start users and/or items problems