

**INTRODUCTION TO CONTINUOUS CONTROL SYSTEMS**  
**COLUMBIA UNIVERSITY MECHANICAL AND ELECTRICAL ENGINEERING**  
**DEPARTMENTS: E3601**

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## Homework 6

**Problem 1** (Laplace Transform). *Show the following:*

$$\int_0^{\infty} t^2 e^{-at} e^{-st} dt = \frac{2}{(s+a)^3} \quad (1)$$

## Solution

*Using integration by parts, with,*

$$\begin{aligned} f &= t^2 \\ g' &= e^{-(s+a)t} \\ g &= -\frac{1}{(s+a)} e^{-(s+a)t} \\ f' &= 2t \end{aligned}$$

*then the integral may be written as,*

$$\int_0^{\infty} t^2 e^{-at} e^{-st} dt \quad (2)$$

$$= [fg]_0^{\infty} - \int_0^{\infty} f'g \quad (3)$$

$$= \left[ -\frac{t^2}{(s+a)} e^{-(s+a)t} \right]_0^{\infty} - \int_0^{\infty} 2t \left( -\frac{1}{(s+a)} e^{-(s+a)t} \right) dt \quad (4)$$

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$$= \frac{2}{(s+a)} \int_0^{\infty} t e^{-(s+a)t} dt \quad (5)$$

Now, we can use integration by parts again using the following definitions,

$$\begin{aligned} f &= t \\ g' &= e^{-(s+a)t} \\ f' &= 1 \\ g &= -\frac{1}{(s+a)} e^{-(s+a)t} \end{aligned}$$

Then,

$$\frac{2}{(s+a)} \int_0^{\infty} t e^{-(s+a)t} dt \quad (6)$$

$$= \frac{2}{(s+a)} \left\{ \left[ -\frac{t}{(s+a)} e^{-(s+a)t} \right]_0^{\infty} - \int_0^{\infty} 1 \left( -\frac{1}{(s+a)} e^{-(s+a)t} \right) dt \right\} \quad (7)$$

$$= \frac{2}{(s+a)^2} \left[ \int_0^{\infty} e^{-(s+a)t} dt \right] \quad (8)$$

$$= \frac{2}{(s+a)^2} \left[ -\frac{1}{(s+a)} e^{-(s+a)t} \right]_0^{\infty} \quad (9)$$

$$= \frac{2}{(s+a)^3} \quad (10)$$

**Problem 2** (Transfer Function). Consider,

$$\begin{aligned} X(s) &= \frac{\omega_n^2}{s(s^2 + 2\zeta\omega_n s + \omega_n^2)} \\ &= \frac{K_0}{s} + \frac{K_{-\alpha+i\omega}}{s+\alpha-i\omega} + \frac{K_{-\alpha-i\omega}}{s+\alpha+i\omega} \end{aligned} \quad (11)$$

We showed that

$$K_{-\alpha+i\omega} = [(s+\alpha-i\omega)X(s)]_{s=-\alpha+i\omega} = \frac{\omega_n^2}{2i\omega(-\alpha+i\omega)} \quad (12)$$

Please show that

$$K_{-\alpha+i\omega} = \frac{\omega_n}{2\omega} e^{-i(\theta+\frac{\pi}{2})} \quad (13)$$

where  $\theta = \tan^{-1}(\frac{\omega}{-\alpha})$

## Solution

$$\begin{aligned}
 \frac{\omega_n^2}{2i\omega(-\alpha + i\omega)} &= \frac{\omega_n^2}{-2\omega(\omega + i\alpha)} \\
 &= \frac{\omega_n^2}{2\omega} \cdot \frac{1}{-(\omega + i\alpha)} \cdot \frac{\omega - i\alpha}{\omega - i\alpha} \\
 &= \frac{\omega_n^2}{2\omega} \cdot \frac{\omega - i\alpha}{-(\omega^2 + \alpha^2)}
 \end{aligned} \tag{14}$$

However,

$$\alpha = \zeta \omega_n \tag{15}$$

and

$$\omega \triangleq \omega_n \sqrt{1 - \zeta^2} \tag{16}$$

Therefore,

$$\begin{aligned}
 \omega^2 &= \omega_n^2 (1 - \zeta^2) \\
 &= \omega_n^2 - \omega_n^2 \zeta^2 \\
 &= \omega_n^2 - \alpha^2
 \end{aligned} \tag{17}$$

or,

$$\omega_n^2 = \omega^2 + \alpha^2 \tag{18}$$

Using equation 18 in equation 14 we have,

$$\begin{aligned}
 \frac{\omega_n^2}{2i\omega(-\alpha + i\omega)} &= \frac{\omega_n}{2\omega} \cdot \frac{(\omega - i\alpha)}{-\sqrt{\omega^2 + \alpha^2}} \\
 &= \frac{\omega_n}{2\omega} \cdot \frac{(-\omega + i\alpha)}{\sqrt{\omega^2 + \alpha^2}}
 \end{aligned} \tag{19}$$

$$\tag{20}$$

Now, let's define  $\theta$  as prescribed in the problem statement,

$$\begin{aligned}
 \theta &\triangleq \tan^{-1} \left( \frac{\omega}{-\alpha} \right) \\
 \Rightarrow \sin(\theta) &= \frac{\omega}{\sqrt{(\omega^2 + \alpha^2)}}
 \end{aligned} \tag{21}$$

$$\cos(\theta) = \frac{-\alpha}{\sqrt{(\omega^2 + \alpha^2)}} \tag{22}$$

$$\tag{23}$$

**Problem 3** (Temporal Response). *Show that equation 24 may be rewritten as 25:*

$$x(t) = u(t) + \frac{\omega_n}{2\omega} \left( e^{-i(\theta + \frac{\pi}{2})} e^{(-\alpha + i\omega)t} + e^{i(\theta + \frac{\pi}{2})} e^{(-\alpha - i\omega)t} \right) \quad (24)$$

$$x(t) = u(t) + \frac{\omega_n}{\omega} e^{-\alpha t} \sin(\omega t - \theta) \quad (25)$$

## Solution

$$\begin{aligned} e^{-i(\theta + \frac{\pi}{2})} e^{(-\alpha + i\omega)t} + e^{i(\theta + \frac{\pi}{2})} e^{(-\alpha - i\omega)t} &= e^{-\alpha t} \left( e^{i(\omega t - \theta + \frac{\pi}{2})} + e^{-i(\omega t - \theta - \frac{\pi}{2})} \right) \\ &= e^{-\alpha t} i \left( e^{i\omega t - \theta} - e^{-i(\omega t - \theta)} \right) \\ &= 2e^{-\alpha t} \sin(\omega t - \theta) \end{aligned} \quad (26)$$

$$x(t) = u(t) + \frac{\omega_n}{\omega} e^{-\alpha t} \sin(\omega t - \theta) \quad (27)$$

**Problem 4** (Use Laplace Transform and Partial Fractions to solve these ODEs).

$$\ddot{y}(t) + 3\dot{y}(t) + 2y(t) = \sin(3t) \quad (28)$$

$$\begin{aligned} y(0) &= -1 \\ \dot{y}(0) &= 0 \end{aligned}$$

(29)

## Solution

*Take the Laplace transform of both sides:*

$$\mathcal{L}\{\ddot{y}(t) + 3\dot{y}(t) + 2y(t)\} = \mathcal{L}\{\sin(3t)\}$$

$$s^2 Y(s) - sy(0) - \dot{y}(0) + 3(sY(s) - y(0)) + 2Y(s) = \frac{3}{s^2 + 9}$$

*Substitute initial conditions  $y(0) = -1, \dot{y}(0) = 0$ :*

$$s^2 Y(s) + s + 3sY(s) + 3 + 2Y(s) = \frac{3}{s^2 + 9}$$

*Combine like terms:*

$$(s^2 + 3s + 2)Y(s) = \frac{3}{s^2 + 9} - (s + 3)$$

$$Y(s) = \frac{3 - (s + 3)(s^2 + 9)}{(s^2 + 9)(s + 1)(s + 2)}$$

$$(s+3)(s^2+9) = s^3 + 3s^2 + 9s + 27 \Rightarrow \text{Numerator} = -s^3 - 3s^2 - 9s - 24$$

$$Y(s) = \frac{-s^3 - 3s^2 - 9s - 24}{(s^2+9)(s+1)(s+2)}$$

$$Y(s) = \frac{A}{s+1} + \frac{B}{s+2} + \frac{Cs+D}{s^2+9}$$

Solving for constants (e.g., using symbolic computation), we get:

$$Y(s) = \frac{10}{13(s+2)} - \frac{17}{10(s+1)} - \frac{3(3s+7)}{130(s^2+9)}$$

Using Laplace inverse formulas:

$$\mathcal{L}^{-1} \left\{ \frac{1}{s+a} \right\} = e^{-at}, \quad \mathcal{L}^{-1} \left\{ \frac{s}{s^2 + \omega^2} \right\} = \cos(\omega t), \quad \mathcal{L}^{-1} \left\{ \frac{1}{s^2 + \omega^2} \right\} = \frac{1}{\omega} \sin(\omega t)$$

Break down:

$$\mathcal{L}^{-1} \left\{ \frac{10}{13(s+2)} \right\} = \frac{10}{13} e^{-2t}$$

$$\mathcal{L}^{-1} \left\{ \frac{17}{10(s+1)} \right\} = \frac{17}{10} e^{-t}$$

$$\mathcal{L}^{-1} \left\{ \frac{-9s}{130(s^2+9)} \right\} = -\frac{9}{130} \cos(3t)$$

$$\mathcal{L}^{-1} \left\{ \frac{-21}{130(s^2+9)} \right\} = -\frac{7}{130} \sin(3t)$$

## Final Answer

$y(t) = \frac{10}{13} e^{-2t} - \frac{17}{10} e^{-t} - \frac{9}{130} \cos(3t) - \frac{7}{130} \sin(3t)$
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### Problem 5.

$$\ddot{y}(t) + 4\dot{y}(t) + 4y(t) = \cos(4t) \tag{30}$$

$$y(0) = 1$$

$$\dot{y}(0) = 1$$

(31)

## Solution

Apply the Laplace transform to both sides:

$$s^2 Y(s) - sy(0) - \dot{y}(0) + 4(sY(s) - y(0)) + 4Y(s) = \frac{s}{s^2 + 16}$$

Substitute the initial conditions:

$$s^2Y(s) - s - 1 + 4sY(s) - 4 + 4Y(s) = \frac{s}{s^2 + 16}$$

$$(s^2 + 4s + 4)Y(s) = \frac{s}{s^2 + 16} + s + 5 \Rightarrow Y(s) = \frac{\frac{s}{s^2 + 16} + s + 5}{(s + 2)^2}$$

Combine the terms over a common denominator:

$$Y(s) = \frac{s}{(s^2 + 16)(s + 2)^2} + \frac{s + 5}{(s + 2)^2}$$

$$Y(s) = \frac{(s + 5)(s^2 + 16) + s}{(s^2 + 16)(s + 2)^2} = \frac{s^3 + 5s^2 + 17s + 80}{(s^2 + 16)(s + 2)^2}$$

$$Y(s) = \frac{-3s + 16}{100(s^2 + 16)} + \frac{103}{100(s + 2)} + \frac{29}{10(s + 2)^2}$$

Using standard Laplace pairs:

$$\mathcal{L}^{-1} \left\{ \frac{s}{s^2 + 16} \right\} = \cos(4t), \quad \mathcal{L}^{-1} \left\{ \frac{1}{s^2 + 16} \right\} = \frac{1}{4} \sin(4t)$$

$$\mathcal{L}^{-1} \left\{ \frac{1}{s + 2} \right\} = e^{-2t}, \quad \mathcal{L}^{-1} \left\{ \frac{1}{(s + 2)^2} \right\} = te^{-2t}$$

Apply term by term:

$$\mathcal{L}^{-1} \left\{ \frac{-3s}{100(s^2 + 16)} \right\} = -\frac{3}{100} \cos(4t)$$

$$\mathcal{L}^{-1} \left\{ \frac{16}{100(s^2 + 16)} \right\} = \frac{1}{25} \sin(4t)$$

$$\mathcal{L}^{-1} \left\{ \frac{103}{100(s + 2)} \right\} = \frac{103}{100} e^{-2t}, \quad \mathcal{L}^{-1} \left\{ \frac{29}{10(s + 2)^2} \right\} = \frac{29}{10} te^{-2t}$$

## Final Answer

$$y(t) = \frac{103}{100} e^{-2t} + \frac{29}{10} te^{-2t} - \frac{3}{100} \cos(4t) + \frac{1}{25} \sin(4t)$$

### Problem 6.

$$\ddot{y}(t) + \dot{y}(t) + y(t) = 1 + \cos(6t) \tag{32}$$

$$y(0) = 0$$

$$\dot{y}(0) = 0$$

(33)

## Solution

Taking the Laplace transform of both sides:

$$\mathcal{L}\{\ddot{y}(t)\} + \mathcal{L}\{\dot{y}(t)\} + \mathcal{L}\{y(t)\} = \mathcal{L}\{1\} + \mathcal{L}\{\cos(6t)\}$$

$$(s^2 Y(s) - sy(0) - \dot{y}(0)) + (sY(s) - y(0)) + Y(s) = \frac{1}{s} + \frac{s}{s^2 + 36}$$

Using initial conditions  $y(0) = 0$ ,  $\dot{y}(0) = 0$ , we simplify:

$$(s^2 + s + 1)Y(s) = \frac{1}{s} + \frac{s}{s^2 + 36}$$

Combine the right-hand side over a common denominator:

$$Y(s) = \frac{2(s^2 + 18)}{s(s^2 + 36)(s^2 + s + 1)}$$

Using symbolic computation, we obtain:

$$Y(s) = \frac{1}{s} - \frac{35s - 36}{1261(s^2 + 36)} - \frac{2(613s + 631)}{1261(s^2 + s + 1)}$$

Use known Laplace inverse pairs:

$$\mathcal{L}^{-1}\left\{\frac{1}{s}\right\} = 1$$

$$\mathcal{L}^{-1}\left\{\frac{-35s + 36}{1261(s^2 + 36)}\right\} = -\frac{35}{1261}\cos(6t) + \frac{6}{1261}\sin(6t)$$

$$\mathcal{L}^{-1}\left\{\frac{-2(613s + 631)}{1261(s^2 + s + 1)}\right\} = -\frac{2}{1261}e^{-t/2}\left(613\cos\left(\frac{\sqrt{3}}{2}t\right) + \frac{1262}{\sqrt{3}}\sin\left(\frac{\sqrt{3}}{2}t\right)\right)$$

## Final Answer

$$y(t) = 1 - \frac{35}{1261}\cos(6t) + \frac{6}{1261}\sin(6t) - \frac{2}{1261}e^{-t/2}\left(613\cos\left(\frac{\sqrt{3}}{2}t\right) + \frac{1262}{\sqrt{3}}\sin\left(\frac{\sqrt{3}}{2}t\right)\right)$$

### Problem 7.

$$\ddot{y}(t) + y(t) = 1 + e^{(-2t)} \tag{34}$$

$$y(0) = 0$$

$$\dot{y}(0) = 0$$

(35)

## Solution

Taking the Laplace transform of both sides:

$$\mathcal{L}\{\ddot{y}(t)\} + \mathcal{L}\{y(t)\} = \mathcal{L}\{1\} + \mathcal{L}\{e^{-2t}\}$$

$$(s^2Y(s) - sy(0) - \dot{y}(0)) + Y(s) = \frac{1}{s} + \frac{1}{s+2}$$

Using the initial conditions  $y(0) = 0$ ,  $\dot{y}(0) = 0$ , we simplify:

$$(s^2 + 1)Y(s) = \frac{1}{s} + \frac{1}{s+2} \Rightarrow Y(s) = \frac{1}{s(s^2 + 1)} + \frac{1}{(s+2)(s^2 + 1)}$$

Combine the terms:

$$Y(s) = \frac{2(s+1)}{s(s+2)(s^2+1)}$$

Using partial fraction decomposition:

$$Y(s) = \frac{1}{s} + \frac{1}{5(s+2)} - \frac{2(3s-1)}{5(s^2+1)}$$

Apply known Laplace inverse formulas:

$$\begin{aligned}\mathcal{L}^{-1}\left\{\frac{1}{s}\right\} &= 1 \\ \mathcal{L}^{-1}\left\{\frac{1}{5(s+2)}\right\} &= \frac{1}{5}e^{-2t} \\ \mathcal{L}^{-1}\left\{\frac{6s}{5(s^2+1)}\right\} &= \frac{6}{5}\cos(t) \\ \mathcal{L}^{-1}\left\{\frac{2}{5(s^2+1)}\right\} &= \frac{2}{5}\sin(t)\end{aligned}$$

So:

$$\mathcal{L}^{-1}\{Y(s)\} = 1 + \frac{1}{5}e^{-2t} - \frac{6}{5}\cos(t) + \frac{2}{5}\sin(t)$$

## Final Answer

$$y(t) = 1 + \frac{1}{5}e^{-2t} - \frac{6}{5}\cos(t) + \frac{2}{5}\sin(t)$$

### Problem 8.

$$\ddot{y}(t) = e^{-5t} \tag{36}$$

$$\begin{aligned}y(0) &= 0 \\ \dot{y}(0) &= 0\end{aligned}$$

(37)

## Solution

Taking the Laplace transform of both sides:

$$\mathcal{L}\{\ddot{y}(t)\} = \mathcal{L}\{e^{-5t}\}$$



$$s^2Y(s) - sy(0) - \dot{y}(0) = \frac{1}{s+5}$$

Using the initial conditions  $y(0) = 0$ ,  $\dot{y}(0) = 0$ , we simplify:

$$s^2Y(s) = \frac{1}{s+5} \Rightarrow Y(s) = \frac{1}{s^2(s+5)}$$

We decompose:

$$\frac{1}{s^2(s+5)} = \frac{A}{s} + \frac{B}{s^2} + \frac{C}{s+5}$$

Solving, we find:

$$Y(s) = \frac{1}{25(s+5)} - \frac{1}{25s} + \frac{1}{5s^2}$$

Using standard Laplace inverse formulas:

$$\mathcal{L}^{-1} \left\{ \frac{1}{s+5} \right\} = e^{-5t}$$

$$\mathcal{L}^{-1} \left\{ \frac{1}{s} \right\} = 1$$

$$\mathcal{L}^{-1} \left\{ \frac{1}{s^2} \right\} = t$$

Apply them:

$$\mathcal{L}^{-1} \{Y(s)\} = \frac{1}{25}e^{-5t} - \frac{1}{25} + \frac{1}{5}t$$

## Final Answer

$$y(t) = \frac{1}{25}e^{-5t} - \frac{1}{25} + \frac{1}{5}t$$

**Problem 9** (Transition Matrix).

Starting with the series definition of  $e^{\mathbf{A}t}$ , compute  $e^{\mathbf{A}t}$  for the following matrices:

## 1A

$$\mathbf{A} = \begin{bmatrix} 1 & 0 \\ 0 & 2 \end{bmatrix} \quad (38)$$

## Solution

$$e^{\mathbf{A}t} \triangleq \mathbf{I} + \mathbf{A}t + \frac{1}{2!}\mathbf{A}^2t^2 + \dots \quad (39)$$

$$= \mathbf{I} + \begin{bmatrix} t & 0 \\ 0 & 2t \end{bmatrix} + \frac{1}{2!} \begin{bmatrix} t^2 & 0 \\ 0 & 4t^2 \end{bmatrix} + \dots \quad (40)$$

$$= \begin{bmatrix} e^t & 0 \\ 0 & e^{2t} \end{bmatrix} \quad (41)$$

## 1B

$$\mathbf{A} = \begin{bmatrix} 2 & 1 \\ 0 & 2 \end{bmatrix} \quad (42)$$

## Solution

$$e^{\mathbf{A}t} \triangleq \mathbf{I} + \mathbf{A}t + \frac{1}{2!}\mathbf{A}^2t^2 + \dots \quad (43)$$

$$= \mathbf{I} + \begin{bmatrix} \lambda & 1 \\ 0 & \lambda \end{bmatrix} t + \frac{1}{2!} \begin{bmatrix} \lambda^2 & 2\lambda \\ 0 & \lambda^2 \end{bmatrix} t^2 + \frac{1}{3!} \begin{bmatrix} \lambda^3 & 3\lambda^2 \\ 0 & \lambda^3 \end{bmatrix} t^3 + \frac{1}{4!} \begin{bmatrix} \lambda^4 & 4\lambda^3 \\ 0 & \lambda^4 \end{bmatrix} t^4 + \dots \quad (44)$$

$$= \begin{bmatrix} \sum_{n=0}^{\infty} \frac{\lambda^n t^n}{n!} & \sum_{n=1}^{\infty} \frac{1}{n!} n \lambda^{n-1} t^n \\ 0 & \sum_{n=0}^{\infty} \frac{\lambda^n t^n}{n!} \end{bmatrix} \quad (45)$$

But

$$\sum_{n=1}^{\infty} \frac{1}{n!} n \lambda^{n-1} t^n = t \sum_{n=1}^{\infty} \frac{1}{(n-1)!} \lambda^{n-1} t^{(n-1)} \quad (46)$$

$$= t \sum_{n=0}^{\infty} \frac{1}{(n)!} \lambda^n t^n \quad (47)$$

$$= t e^{\lambda t} \quad (48)$$

Therefore,

$$e^{\mathbf{A}t} = \begin{bmatrix} e^{\lambda t} & t e^{\lambda t} \\ 0 & e^{\lambda t} \end{bmatrix} \quad (49)$$

### Problem 10.

#### Part A

Solve for  $\mathbf{x}(t)$  in the following:

$$\dot{\vec{x}}(t) = \begin{bmatrix} -1 & 2 \\ -2 & -1 \end{bmatrix} \vec{x}(t) \quad (50)$$

$$\vec{x}(0) = \begin{bmatrix} 0 \\ 1 \end{bmatrix} \quad (51)$$

## Solution

$$\mathbf{x}(t) = C \mathbf{v} e^{st} \quad (52)$$

$$\cancel{C} s \cancel{\mathbf{v}} \cancel{e}^{st} = \mathbf{A} \cancel{C} \cancel{\mathbf{v}} \cancel{e}^{st} \quad (53)$$

$$\mathbf{A} \mathbf{v} = s \mathbf{v} \quad (54)$$

$$(\mathbf{A} - s \mathbf{I}) \mathbf{v} = 0 \quad (55)$$

$$|\mathbf{A} - s\mathbf{I}| = 0 \quad (56)$$

$$\left| \begin{bmatrix} -1 & 2 \\ -2 & -1 \end{bmatrix} - \begin{bmatrix} s & 0 \\ 0 & s \end{bmatrix} \right| = 0 \quad (57)$$

$$\left| \begin{array}{cc} -1-s & 2 \\ -2 & -1-s \end{array} \right| = 0 \quad (58)$$

$$s^2 + 2s + 5 = 0 \quad (59)$$

$$s_{1,2} = \frac{-2 \pm \sqrt{4-20}}{2} \quad (60)$$

$$= -1 \pm 2i \quad (61)$$

$$\left( \begin{bmatrix} -1 & 2 \\ -2 & -1 \end{bmatrix} - \begin{bmatrix} -1+2i & 0 \\ 0 & -1+2i \end{bmatrix} \right) \begin{bmatrix} v_{1,1} \\ v_{1,2} \end{bmatrix} = \begin{bmatrix} 0 \\ 0 \end{bmatrix} \quad (62)$$

$$\begin{bmatrix} -2i & 2 \\ -2 & -2i \end{bmatrix} \begin{bmatrix} v_{1,1} \\ v_{1,2} \end{bmatrix} = \begin{bmatrix} 0 \\ 0 \end{bmatrix} \quad (63)$$

$$\begin{bmatrix} v_{1,1} \\ v_{1,2} \end{bmatrix} = \begin{bmatrix} -i \\ 1 \end{bmatrix} \quad (64)$$

$$\left( \begin{bmatrix} -1 & 2 \\ -2 & -1 \end{bmatrix} - \begin{bmatrix} -1-2i & 0 \\ 0 & -1-2i \end{bmatrix} \right) \begin{bmatrix} v_{2,1} \\ v_{2,2} \end{bmatrix} = \begin{bmatrix} 0 \\ 0 \end{bmatrix} \quad (65)$$

$$\begin{bmatrix} 2i & 2 \\ -2 & 2i \end{bmatrix} \begin{bmatrix} v_{2,1} \\ v_{2,2} \end{bmatrix} = \begin{bmatrix} 0 \\ 0 \end{bmatrix} \quad (66)$$

$$\begin{bmatrix} v_{2,1} \\ v_{2,2} \end{bmatrix} = \begin{bmatrix} 1 \\ -i \end{bmatrix} \quad (67)$$

$$\begin{aligned} \vec{x}(t) &= c_1 \begin{pmatrix} -i \\ 1 \end{pmatrix} e^{(-1+2i)t} + c_2 \begin{pmatrix} 1 \\ -i \end{pmatrix} e^{(-1-2i)t} \\ &= e^{-t} \left[ c_1 \begin{pmatrix} -i \\ 1 \end{pmatrix} e^{2it} + c_2 \begin{pmatrix} 1 \\ -i \end{pmatrix} e^{-2it} \right] \end{aligned} \quad (68)$$

$$\vec{x}(0) = \begin{pmatrix} 0 \\ 1 \end{pmatrix} \implies c_1 \begin{pmatrix} -i \\ 1 \end{pmatrix} + c_2 \begin{pmatrix} 1 \\ -1 \end{pmatrix} = \begin{pmatrix} 0 \\ 1 \end{pmatrix} \quad (69)$$

$$i[-ic_1 + c_2 = 0] \implies c_1 + ic_2 = 0 \quad (70)$$

also,

$$c_1 - ic_2 = 1 \quad (71)$$

Therefore,

$$2c_1 = 1 \implies \boxed{c_1 = \frac{1}{2}} \quad (72)$$

$$\frac{1}{2} + ic_2 = 0 \implies \boxed{c_2 = -\frac{1}{2i} = i\frac{1}{2}} \quad (73)$$

$$\begin{aligned} \vec{x}(t) &= e^{-t} \left[ c_1 \begin{pmatrix} -i \\ 1 \end{pmatrix} e^{2it} + c_2 \begin{pmatrix} 1 \\ -1 \end{pmatrix} e^{-2it} \right] \\ &= e^{-t} \left[ \frac{1}{2} \begin{pmatrix} -i \\ 1 \end{pmatrix} e^{2it} + \frac{1}{2} i \begin{pmatrix} 1 \\ -1 \end{pmatrix} e^{-2it} \right] \\ &= e^{-t} \left[ \frac{1}{2} \begin{pmatrix} -i \cos(2t) + \sin(2t) \\ \cos(2t) + i \sin(2t) \end{pmatrix} + \frac{1}{2} i \begin{pmatrix} \cos(2t) - i \sin(2t) \\ -\cos(2t) - \sin(2t) \end{pmatrix} \right] \\ &= e^{-t} \left[ \begin{pmatrix} -\frac{1}{2} i \cos(2t) + \frac{1}{2} \sin(2t) + \frac{1}{2} i \cos(2t) + \frac{1}{2} \sin(2t) \\ \frac{1}{2} \cos(2t) + \frac{1}{2} i \sin(2t) + \frac{1}{2} \cos(2t) - \frac{1}{2} i \sin(2t) \end{pmatrix} \right] \\ &= e^{-t} \begin{pmatrix} \sin(2t) \\ \cos(2t) \end{pmatrix} \end{aligned} \quad (74)$$

### Part B

Compute  $e^{At}$  for

$$\mathbf{A} = \begin{bmatrix} -1 & 2 \\ -2 & -1 \end{bmatrix} \quad (75)$$

using the series definition of  $e^{At}$ .

### Solution

$$e^{At} = \sum_{n=0}^{\infty} \frac{(At)^n}{n!} \quad (76)$$

$$\begin{aligned} \mathbf{A} &= \begin{bmatrix} -1 & 2 \\ -2 & -1 \end{bmatrix} \\ &= \begin{bmatrix} \sigma & \omega \\ -\omega & \sigma \end{bmatrix} \end{aligned}$$

where,  $\sigma = -1$  and  $\omega = 2$ .

$$\begin{aligned} e^{\begin{bmatrix} \sigma & \omega \\ -\omega & \sigma \end{bmatrix} t} &= e^{\left( \sigma \mathbf{I} + \begin{bmatrix} 0 & \omega \\ -\omega & 0 \end{bmatrix} \right) t} \\ &= e^{\sigma t} e^{\begin{bmatrix} 0 & \omega \\ -\omega & 0 \end{bmatrix} t} \end{aligned} \quad (77)$$

$$\begin{aligned} e^{\begin{bmatrix} 0 & \omega \\ -\omega & 0 \end{bmatrix} t} &= \begin{bmatrix} 1 & 0 \\ 0 & 1 \end{bmatrix} + \begin{bmatrix} 0 & \omega \\ -\omega & 0 \end{bmatrix} t + \frac{1}{2!} \begin{bmatrix} \omega^2 & 0 \\ 0 & -\omega^2 \end{bmatrix} t^2 \\ &+ \frac{1}{3!} \begin{bmatrix} 0 & -\omega^3 \\ \omega^3 & 0 \end{bmatrix} t^3 + \frac{1}{4!} \begin{bmatrix} \omega^4 & 0 \\ 0 & \omega^4 \end{bmatrix} t^4 \\ &+ \frac{1}{5!} \begin{bmatrix} 0 & \omega^5 \\ -\omega^5 & 0 \end{bmatrix} t^5 + \dots \end{aligned} \quad (78)$$

$$\begin{aligned} e^{\begin{bmatrix} 0 & \omega \\ -\omega & 0 \end{bmatrix} t} &= \begin{bmatrix} 1 & 0 \\ 0 & 1 \end{bmatrix} + \frac{1}{2!} \begin{bmatrix} \omega^2 & 0 \\ 0 & -\omega^2 \end{bmatrix} t^2 + \frac{1}{4!} \begin{bmatrix} \omega^4 & 0 \\ 0 & \omega^4 \end{bmatrix} t^4 \\ &+ \begin{bmatrix} 0 & \omega \\ -\omega & 0 \end{bmatrix} t + \frac{1}{3!} \begin{bmatrix} 0 & -\omega^3 \\ \omega^3 & 0 \end{bmatrix} t^3 + \frac{1}{5!} \begin{bmatrix} 0 & \omega^5 \\ -\omega^5 & 0 \end{bmatrix} t^5 + \dots \end{aligned} \quad (79)$$

$$\begin{aligned} e^{\begin{bmatrix} 0 & \omega \\ -\omega & 0 \end{bmatrix} t} &= \begin{bmatrix} \cos(\omega t) & 0 \\ 0 & \cos(\omega t) \end{bmatrix} + \begin{bmatrix} 0 & \sin(\omega t) \\ -\sin(\omega t) & 0 \end{bmatrix} \\ &= \begin{bmatrix} \cos(\omega t) & \sin(\omega t) \\ -\sin(\omega t) & \cos(\omega t) \end{bmatrix} \end{aligned} \quad (80)$$

$$\begin{aligned}
e^{\mathbf{A}t} &= \begin{pmatrix} e^{\sigma t} & 0 \\ 0 & e^{\sigma t} \end{pmatrix} \begin{bmatrix} \cos(\omega t) & \sin(\omega t) \\ -\sin(\omega t) & \cos(\omega t) \end{bmatrix} \\
&= \begin{bmatrix} e^{\sigma t} \cos(\omega t) & e^{\sigma t} \sin(\omega t) \\ -e^{\sigma t} \sin(\omega t) & e^{\sigma t} \cos(\omega t) \end{bmatrix}
\end{aligned} \tag{81}$$