

INTRODUCTION TO CONTINUOUS CONTROL SYSTEMS
COLUMBIA UNIVERSITY MECHANICAL AND ELECTRICAL ENGINEERING
DEPARTMENTS: E3601

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Homework 8

Problem 1 (Simulink Exercise).

Use the Matlab Simulink to implement the following system:

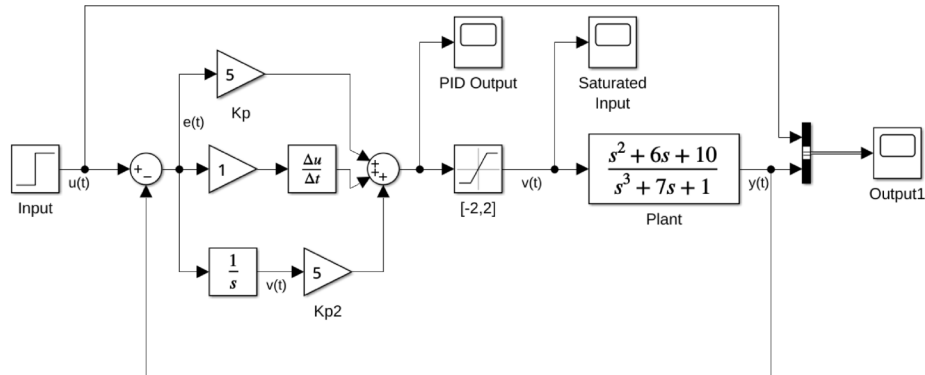


Fig. 1: Simulink PID Control Implementation with a Unit Step Input

Submit the Simulink (.slx) file along with the outputs from the three different scopes in the figure in a .zip or .tgz file.*

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