

INTRODUCTION TO CONTINUOUS CONTROL SYSTEMS
COLUMBIA UNIVERSITY MECHANICAL AND ELECTRICAL ENGINEERING
DEPARTMENTS: E3601

Homayoon Beigi[†]

1340 Mudd Building
Columbia University, New York City, NY 10027
hb87@columbia.edu

Homework 7

Problem 1 (Characteristic Equation and Eigenvalues).

Write the characteristic equations, Eigenvalues, and Eigenvectors of the following matrices.

$$\mathbf{A} = \begin{bmatrix} 2 & 1 \\ 4 & 9 \end{bmatrix} \quad (1)$$

$$\mathbf{A} = \begin{bmatrix} 1 & -1 & 5 \\ 0 & -7 & 3 \\ -1 & -6 & -2 \end{bmatrix} \quad (2)$$

Problem 2 (Similarity Transform).

Find the Eigenvalues and Eigenvectors of the following matrix and convert the matrices into diagonal or block diagonal form, whichever is appropriate.

$$\mathbf{A} = \begin{bmatrix} 1 & 2 \\ 5 & 4 \end{bmatrix} \quad (3)$$

$$\mathbf{A} = \begin{bmatrix} 1 & 2 \\ 2 & 4 \end{bmatrix} \quad (4)$$

$$\mathbf{A} = \begin{bmatrix} 1 & 2 & 0 \\ -1 & 3 & 0 \\ 2 & -4 & 3 \end{bmatrix} \quad (5)$$

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[†]Homayoon Beigi is Professor of Professional Practice in the department of mechanical engineering and in the department of electrical engineering at Columbia University

Problem 3. Prove the following Theorem:

Theorem 1 (Complex Conjugate Eigenvalues). Suppose \mathbf{A} has the following eigenvalues,

$$\lambda_i = \sigma_i + i\omega_i \quad (6)$$

$$\lambda_{i+1} = \sigma_i - i\omega_i = \bar{\lambda}_i \quad (7)$$

$$(8)$$

for $i = \{1, 3, 5, \dots, m-1\}$ and

$$\lambda_i = \bar{\lambda}_i \quad (9)$$

for $i = \{m+1, m+2, \dots, n\}$

and a linealy independent set of eigenvectors

$$\mathbf{u}_i = \mathbf{v}_i + i\mathbf{w}_i \quad (10)$$

$$\mathbf{u}_{i+1} = \mathbf{v}_i - i\mathbf{w}_i = \bar{\mathbf{u}}_i \quad (11)$$

$$(12)$$

for $i = \{1, 3, 5, \dots, m-1\}$ and

$$\mathbf{u}_i = \bar{\mathbf{u}}_i \quad (13)$$

for $i = \{m+1, m+2, \dots, n\}$

The, the real-valued matrix,

$$\mathbf{U} = [\mathbf{v}_1 \ \mathbf{w}_1 \ \mathbf{v}_3 \ \mathbf{w}_3 \ \dots \ \mathbf{v}_{m-1} \ \mathbf{w}_{m-1} \ \mathbf{u}_{m+1} \ \mathbf{u}_{n-1} \ \dots \ \mathbf{u}_n] \quad (14)$$

is nonsingular and may be used to transform \mathbf{A} into the block-diagram form,

$$\mathbf{U}^{-1}\mathbf{A}\mathbf{U} = \begin{bmatrix} \mathbf{\Lambda}_1 & 0 & \dots & 0 & 0 \\ 0 & \mathbf{\Lambda}_3 & \dots & 0 & 0 \\ \dots & \dots & \dots & \ddots & \vdots \\ 0 & 0 & \dots & \mathbf{\Lambda}_{m-1} & 0 \\ 0 & 0 & 0 & \dots & \mathbf{\Lambda}_{m+1} \end{bmatrix} \quad (15)$$

where,

$$\mathbf{\Lambda}_i = \begin{bmatrix} \sigma_i & \omega_i \\ -\omega_i & \sigma_i \end{bmatrix} \quad (16)$$

for $i = \{1, 3, 5, \dots, m-1\}$ and

$$\mathbf{\Lambda}_{m+1} = \begin{bmatrix} \lambda_{m+1} & 0 & \dots & 0 & 0 \\ 0 & \lambda_{m+2} & \dots & 0 & 0 \\ \dots & \dots & \dots & \ddots & \vdots \\ 0 & 0 & \dots & \lambda_{n-1} & 0 \\ 0 & 0 & 0 & \dots & \lambda_n \end{bmatrix} \quad (17)$$

This result also holds for non-distinct eigenvalues, provided that the eigenvectors are linearly independent.

Hint:

First show that

$$\mathbf{A}\mathbf{v}_i = \sigma_i\mathbf{v}_i - \omega_i\mathbf{w}_i \quad (18)$$

$$\mathbf{A}\mathbf{w}_i = \omega_i\mathbf{v}_i + \sigma_i\mathbf{w}_i \quad (19)$$

for $i = \{1, 3, 5, \dots, m-1\}$ and then proceed as if you have all diagonal elements.

Problem 4. If $\mathbf{A} : \mathcal{R}^n \mapsto \mathcal{R}^n$ and $m \geq n$, show that \mathbf{A}^m may be written as,

$$\mathbf{A}^m = \lambda_0 \mathbf{I} + \lambda_1 \mathbf{A} + \lambda_2 \mathbf{A}^2 + \dots + \lambda_{n-1} \mathbf{A}^{n-1} \quad (20)$$

for some coefficients λ_i .

Hint:

Use the Cayley-Hamilton theorem recursively.